

A PRINTER PLOTTER PROGRAM FOR
DIGITAL SIMULATION STUDIES

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Many computer simulation experiments involve the generation of large quantities of output data, resulting in extensive tables of numerical information. These tables are often difficult to interpret without considerable effort on the part of the reader, particularly with respect to the detection of variable trend perturbations in long strings of data. To alleviate this difficulty, a computer subroutine was developed to provide immediate printer plots of data arrays generated in simulation program runs. These plots allow the immediate examination of experimental run results, and provide the user with an easy-to-read tool for determining requirements for additional computer runs.

The program will plot up to five simultaneous data curves, with automatic plot variable scaling on each curve to achieve maximum output resolution in each instance. If the user wishes to plot any number of curves less than the five maximum allowed on a given set of axes, it is only necessary to fill the unused arrays appearing in the call statement with some common constant value, and the curve for this array or group of arrays will not be plotted. Similarly, simulation program outputs with more than five variables can easily be accommodated with multiple calls to the plotting program.

The plot routine was written in IBM 1130 FORTRAN, but should be acceptable to any FORTRAN compiler with an alphanumeric capability and provisions for a DATA statement. In fact, the authors use the same program deck on both IBM 1130 and IBM 360/65 computer runs, with the only change required being the appropriate selection for the FORTRAN logical unit number for the output printer. A complete listing of the program appears in figure 1.

The plotter is called from the data generation program with a statement of the following form:

CALL YPLOT(NPTS, A, B, C, D, E, X, IFLAG)

where: NPTS = scalar integer variable giving the number of points to be plotted. The subroutine presently uses variable dimension array allocation to conserve memory requirements, and the reader should be aware that this feature may cause difficulties in other FORTRAN implementations.

A, B, C, D, E, = one dimensional FORTRAN arrays of length 'NPTS' containing the data points to be plotted.

X = one dimensional FORTRAN array of length 'NPTS' containing the values of the common independent variable values for each of the five data curves.

Figure 1. Plotter Program Listing (1 of 3)

Figure 1. Plotter Program Listing (2 of 3)

FORTRAN IV C LEVEL 19 YPLOT DATE = 71177 14347/24 PAGE 0003
 0098 155 WRITE(IJ,117) ZZ(L), (X(MM), MM=1,100)
 0099 117 FORMAT (1X, F8.2,100A1)
 0100 77 IF ((L/10) - (Z/10) .EQ. 0) 45,46,45
 0101 46 DD 47 KL = 1,100
 0102 47 X(KL) = BL
 0103 45 IF (NK = 50) 153,156,154
 0104 154 NK = 0
 0105 153 NK = NK + 1
 0106 IF (AUNIT) 400,401,400
 0107 400 X(KA) = BL
 0108 401 IF (BUNIT) 402,403,402
 0109 402 X(KB) = BL
 0110 403 IF (CUNIT) 404,405,404
 0111 404 X(KC) = BL
 0112 405 IF (DUNIT) 406,407,406
 0113 406 X(KD) = BL
 0114 407 IF (EUNIT) 408,1000,408
 0115 408 X(KE) = BL
 0116 1000 CONTINUE
 0117 RETURN
 0118 END

Figure 1. Plotter Program Listing (3 of 3)

EACH UNIT ON THE Y -AXIS = 0.85610 FOR EQ. A , 0.65424 FOR EQ. B , 0.20000 FOR EQ. C ,
 0.25631 FOR EQ. D , 0.0 FOR EQ. E

314.59009	357.29492	400.00000
200.00000	232.71179	265.42358
100.00000	109.99994	119.99989
100.00000	112.81557	125.63115
120.00000	120.00000	120.00000
*	*	*
1D	I	A
2D	B	I
3I	D	I
4I	D	B
5I	A	I
6I	A	D
7A	I	I
8A	I	I
9A	I	I
10I	A	I
11I	A	I
12I	A	I
13I	A	I
14I	I	A
15I	I	A
16I	I	A
17I	I	A
18I	I	A
19I	I	A
20I	I	A
21I	I	A
22I	I	A
23I	I	A
24I	I	A
25I	I	A
26I	E	A
27I	I	A
28I	I	A
29I	I	A
30I	I	A
31I	I	A
32I	I	A
33I	I	A
34I	I	A
35I	I	A
36I	I	A
37I	I	A
38I	I	A
39I	I	A
40I	I	A
41I	I	A
42I	I	A
43I	I	A
44I	I	A
45I	I	A
46I	I	A
47I	I	A
48I	I	A
49I	I	A
50I	I	A

Figure 2. Plotter Output for Simulation Example

IFLAG = scalar integer control variable. If set equal to zero, the program will ignore the values in the X array and print an integer count of the data point numbers at the left of each row of the output plot. If set equal to one, the program will print the appropriate values from the X array at the left of each row of the output plot.

To illustrate the use of the program in a representative simulation study, consider the simple production-inventory system described in (1). The model equations are given in the reference in the DYNAMO Computer Language format, but may easily be converted to a state-variable differential equation following the procedure outlined in (2). Assuming a state vector definition of the form:

$$\underline{X} = \begin{bmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \\ X_5 \end{bmatrix} = \begin{bmatrix} \text{Retail Inventory} \\ \text{Factory Order Backlog} \\ \text{Averaged Retail Sales} \\ \text{Production Ability} \\ \text{Retail Sales} \end{bmatrix}$$

the simulation model then becomes the fifth-order system:

$$\dot{\underline{X}} = \underline{AX}$$

with

$$\underline{A} = \begin{bmatrix} 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & -1 & 0 & 1 \\ 0 & .125 & 0 & -.25 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

A state-transition matrix data generation program was used to exercise the model with the initial conditions specified in the reference over a time frame of 0 to 49 units and a step size of 1 unit, giving a total of 50 state vector output points of 5 components each. The state vector values were incrementally loaded into the plot arrays as the simulation progressed. The plotter routine was called at the end of the numerical processing, with the results shown in figure 2. The first four curves, representing the first four components of the state vector, were plotted with the characters A, B, C, and D respectively. The minimum, maximum, and mid-point values for each curve appear at the top of each page of the output in ascending order. Note that the values for E are constant at a level of 120.000, indicating that the fifth state vector component remained at this constant value throughout the run. This aspect of program behavior is also used when plotting less than the full complement of five curves, as the data in a constant vector would plot as a straight vertical line, and are deleted from the plot output to maximize readability. Also note that the plot in figure 2 used IFLAG = 0, and the data point count generated by the plotter appears in the left hand margin.

A brief note about the scaling procedures employed by the program is in order. Under normal operating conditions, scaling is accomplished automatically for each curve without user intervention. If, however, a common scale for each of the five curves is required, the main program must be structured to supply the upper and lower limits of each curve's plot scale in two entries appended to each data array, and to set the point counter to a value equal to the number of the actual data points to be plotted plus two to force the scaling section to consider the supplied values. In order for this procedure to work properly, the lower limit specified must be less than or equal to the smaller expected data point, and similarly, the upper plot limit must be greater than or equal to the largest expected data point.